

Bandits for large scale problems

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(CA 1488/1-1)

Based on joint works with : **Rémi Munos, Michal Valko**

January 12, 2016

Bandits for large scale problems

In the classical bandit setting, it is usually assumed that the number of actions A is smaller than the horizon n , i.e.

$$A \leq n,$$

so that each action can be sampled at least once.

Here large scale problems are problems where $A \gg n$.

Outline

Bandits with alternative objectives

- The bandit setting

- Some alternative objectives

Large scale problems ($A \gg n$)

- Linear topology

- Smooth topology

- No topology

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- Linear topology

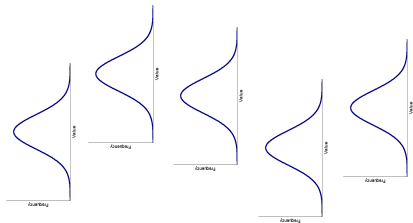
- Smooth topology

- No topology

Stochastic bandit setting

Resource allocation in face of uncertainty See [Thompson (1933)], [Robbins (1952)], [Gittins (1979)], etc.

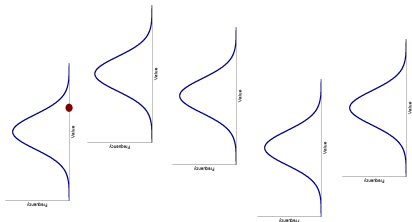
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- ▶ Limited sampling resources n
- ▶ At each time t , choose a_t and collect $X_t \sim \nu_{a_t}$
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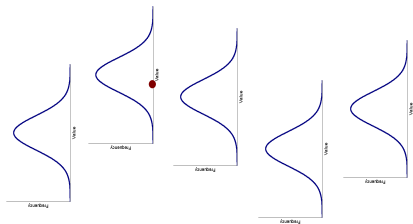
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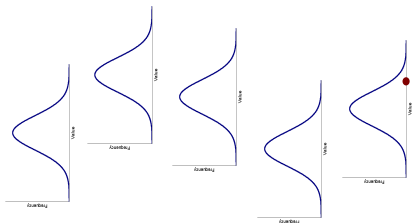
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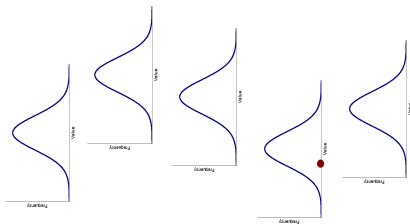
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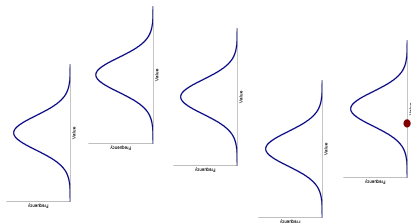
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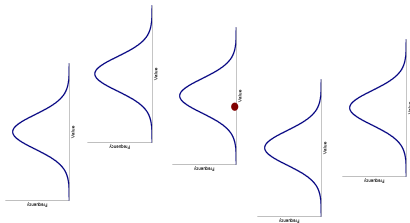
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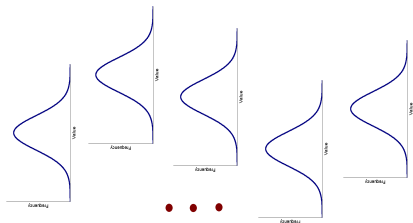
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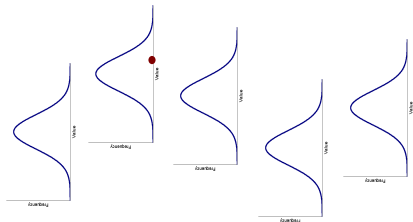
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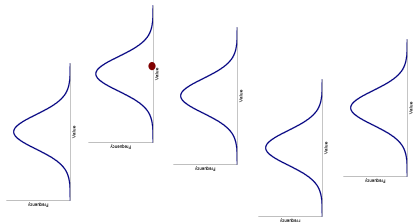
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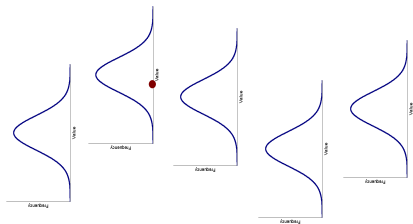
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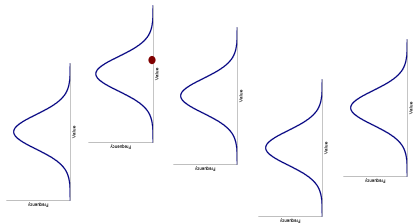
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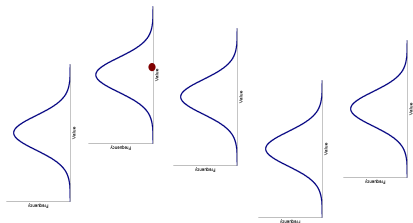
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Objective of allocation when e.g. maximizing $\sum_t X_t$:

- ▶ Estimate all means μ_a of distributions (exploration)
- ▶ So that one finds the one with highest mean μ^* and samples it (exploitation)

Because of the noise to the samples, there is this exploration/exploitation trade-off.

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Popular solution to this trade-off is to sample the arm that maximizes an UCB [Auer et.al.(2002)] :

$$B_{a,t} = \hat{\mu}_{a,t} + c \sqrt{\frac{\log(n)}{T_{a,t}}}.$$

Theorem

The exp. regret is bounded as

$$\begin{aligned} \mathbb{E}R_n &= n\mu^* - \mathbb{E} \sum_t X_t \\ &\leq c\sqrt{nA \log(n)}. \end{aligned}$$

Stochastic bandit setting

Main question in this talk is on the *scale* of the problem.

Large scale aim

$$A \gg n.$$

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Possible alternative objectives :

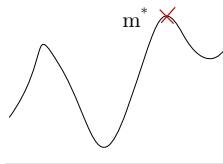
- ▶ **Noisy optimisation** Bubeck et al., 2010, Kaufman et al., 2012, Gabillon et al., 2012, Valko et al., 2013.
- ▶ **Uniform functional estimation** Antos et al., 2010, C et al., 2012, C et al., 2013.
- ▶ **Stratified Monte-Carlo integration** Grover et al., 2010, C et al., 2012, 2013, 2014.
- ▶ **Extreme value detection** Smith et al, 2009, C and Valko, 2014.

Noisy optimisation [Kleinberg et. al, 2008, Bubeck et al., 2010, Kaufman et al., 2012, Gabillon et al., 2012]

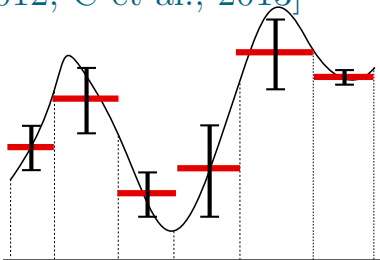
In the cumulative bandit setting, the objective is

$$\max \sum_t X_t.$$

A useful variant is the *pure exploration* variant of this setting where the aim is to return at the end of the budget \hat{k}_n such that $\mu_{\hat{k}_n}$ is as large as possible (as close as possible to the optimal value μ^*). This is *noisy optimisation* in the bandit setting.



Adaptive stratified functional estimation [Antos et al., 2010, C et al., 2012, C et al., 2013]

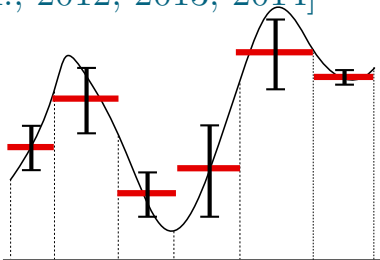


Each stratum has measure w_k and sampling randomly in it results in a sample $X \sim \nu_k(\mu_k, \sigma_k^2)$.

Objective : Sample optimally in the strata to estimate the integral μ of the function and minimize

$$\max_k \mathbb{E}(\hat{\mu}_k - \mu_k)^2 = \max_k \frac{\sigma_k^2}{T_k}.$$

Adaptive stratified Monte-Carlo integration [Grover et al., 2010, C et al., 2012, 2013, 2014]



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The “large scale” situation

Two main lines of work in order to solve this problem :

1. Topological assumptions on the distributions :

There is a topology on the distributions so that information on a distribution provides information on other options as well. Examples :

1.1 Linear topology.

1.2 Smooth topology.

2. No Topological assumptions on the distributions :

There is no topology on the options. Can represent also smooth topology in high dimension.

Linear topology : setting [Auer, 2002]

Problem : The set of arms \mathcal{A} is a subset of \mathbb{R}^D , and $\alpha^* \in \mathbb{R}^D$ is an unknown parameter. At each time step t ,

- ▶ Select $a_t \in \mathcal{A}$,
- ▶ Observe $X_t = \langle a_t, \alpha^* \rangle + \eta_t$, where $\mathbb{E}[\eta_t | a_t] = 0$.

Let $a^* = \arg \max_{a \in \mathcal{A}} \langle a, \alpha^* \rangle$ be the best arm in \mathcal{A} .

Define the regret:

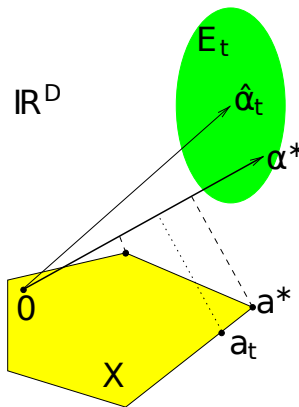
$$\mathbb{E}R_n = n \langle a^*, \alpha^* \rangle - \mathbb{E} \sum_{t=1}^n X_t.$$

No need to estimate the mean-reward of all arms, estimating α^* is enough [Auer, 2002], [Dani, Hayes, Kakade, 2008], [Abbasi-Yadkori, 2009], [Rusmevichientong, Tsitsiklis, 2010], [Filippi, Cappé, Garivier, Szepesvári, 2010].

Linear topology : UCB-based (ConfidenceBall) algorithm

Idea: Build a high probability confidence set E_t s.t. $\alpha^* \in E_t$ w.h.p. and play the arm $a \in \mathcal{A}$ that maximizes

$$B_{a,t} = \max_{\alpha \in E_t} \langle a, \alpha \rangle.$$



Linear Topology : Regret analysis and extensions

Theorem ((Dani, Hayes, Kakade, 2008, Rusmevichientong, Tsitsiklis, 2010))

The expected regret of ConfidenceBall is bounded as

$$\mathbb{E}R_n \leq D\sqrt{n}(\log n)^{3/2}$$

Possible extensions

- ▶ **Generalized Linear models** [Filippi, Cappé, Garivier, Szepesvári, 2010]..
- ▶ **Sparse linear bandits in high dimension** [C and Munos, 2012].

Extension to high dimensional and sparse linear bandits [C and Munos, 2012]

Linear bandit algorithm work if $D \ll n$. But what if $D \geq n$? In general nothing is possible but under the assumption that α^* is k -sparse and that \mathcal{A} is the unit-ball, a solution is to first explore the space at random until the support of the signal is detected (CS phase) approximately, and then run ConfidenceBall on the right support (SL-UCB).

Theorem (C and Munos, 2012)

The expected regret of SL-UCB is bounded as

$$\mathbb{E}R_n \leq k\sqrt{n}(\log D)^{3/2}$$

Smooth topology : setting [Kleinberg et.al., 2008]

Problem: Let $f : \mathcal{A} \rightarrow \mathbb{R}$, assumed to be Lipschitz:

$$|f(x) - f(y)| \leq \ell(x, y).$$

- ▶ At each time step t , select $a_t \in \mathcal{A}$
- ▶ Observe $X_t = f(a_t) + \eta_t$

Define the cumulative regret

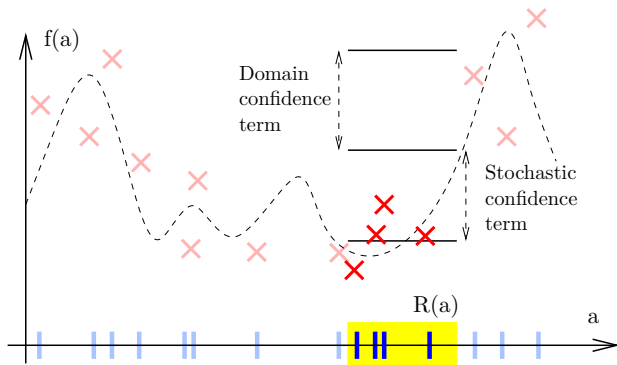
$$R_n = nf^* - \sum_{t=1}^n X_t,$$

where $f^* = \sup_{a \in \mathcal{A}} f(a)$

Continuous stochastic optimization as a bandit problem

[Kleinberg et.al., 2008, Srinivas et.al., 2009, Grünewälder et.al., 2010, Krause et.al., 2011, Bubeck et.al., 2010, Valko et.al., 2013].

Smooth topology : UCB-based (HOO) algorithm



Idea : Choose a small region $R(a)$ around a and sample the arm that maximizes

$$B_{a,t} = \hat{\mu}_{R(a),t} + SCT(a) + DCT(a).$$

Smooth Topology : Regret analysis

Theorem ((Kleinberg et.al., 2008, Bubeck et.al., 2010))

Let d be the **near-optimality dimension** of f in \mathcal{A} : i.e. such that the set of ϵ -optimal actions

$$X_\epsilon = \{x \in \mathcal{A}, f(x) \geq f^* - \epsilon\}$$

can be covered by $O(\epsilon^{-d})$ balls of radius ϵ .

The expected regret of HOO is bounded as

$$\mathbb{E}R_n \leq Dn^{\frac{d+1}{d+2}}.$$

Extensions

- ▶ Unknown smoothness [Munos, 2013, Bull, 2014, Valko et al, 2015].
- ▶ Simple regret [Valko et.al., 2013].
- ▶ Continuous MC integration [C and Munos, 2013 a)b), 2014], [Pietquin et al., 2013].
- ▶ Uniform functional estimation [C and Maillard, 2013, Bull, 2013].

Continuous MC integration [C and Munos, 2014]

Assume that we want to integrate the function f and we can sample it n times and get at time t if sampling in x_t

$$y_t = f(x_t) + s(t)\eta_t,$$

where $\mathbb{V}(\eta_t) = 1$. The oracle optimal sampling strategy has risk $\frac{(\int_{\mathcal{X}} s(x)dx)^2}{n}$.

Theorem

Assume that $|f(x) - f(y)| \leq \ell(x, y) = L\|x - y\|^\alpha$ and s also α -Hölder and $\mathcal{A} = [0, 1]^D$. Then algorithm MC-ULCB outputting $\hat{\mu}_n$ estimating $\int f$ satisfies

$$\mathbb{E}(\hat{\mu}_n - \int f)^2 - \frac{(\int s(x)dx)^2}{n} \leq CD^{\frac{2\alpha}{3d} + \frac{1}{2}} \sqrt{\log(n)} n^{-\frac{d+4\alpha}{d+3\alpha}}.$$

No topology : setting [Berry, Chen, Zame, Heath, Shepp, 1997]

Problem: Solve the stochastic bandit problem with $A \gg n$ (potentially $A = \infty$).

- ▶ At each time step t , select $a_t \in \mathcal{A}$
- ▶ Observe $X_t \sim \nu_{a_t}$

Define the cumulative regret

$$R_n = n\mu^* - \sum_{t=1}^n X_t,$$

where $\mu^* = \sup_{a \in \mathcal{A}} \mu_k$

Standard strategies do not apply when $A \gg n$ - need to sub-sample [Banks, Sundaram, 1992], [Berry, Chen, Zame, Heath, Shepp, 1997], [Wang, Audibert, Munos, 2008], [Bonald and Proutiere, 2008], [C and Valko, 2015].

No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

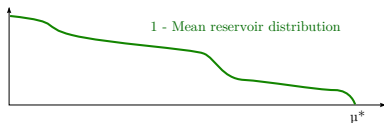
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 0$:



No topology setting

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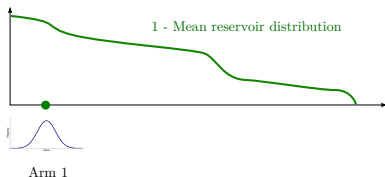
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Objective : Maximize $\sum_t X_t$.

At time $t = 1$:



No topology setting

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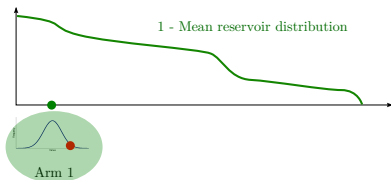
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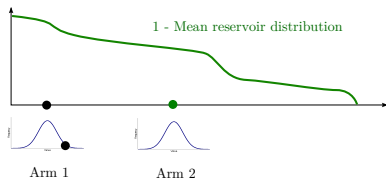
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Objective : Maximize $\sum_t X_t$.

At time $t = 2$:



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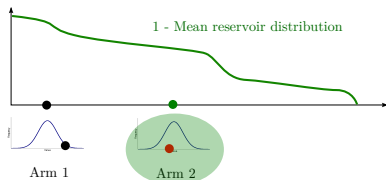
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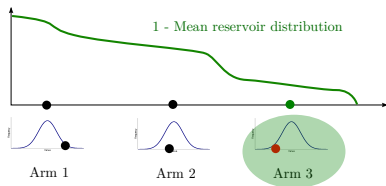
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Objective : Maximize $\sum_t X_t$.

At time $t = 3$:



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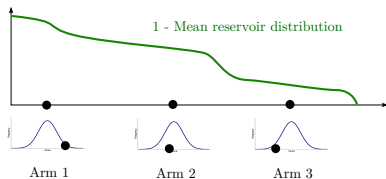
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 3$:



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

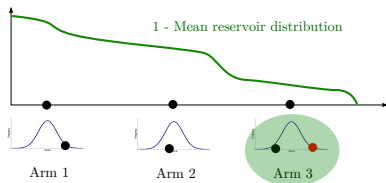
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 4$:



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

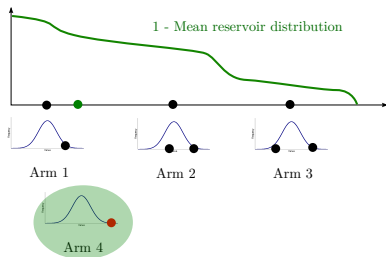
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 5$:



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

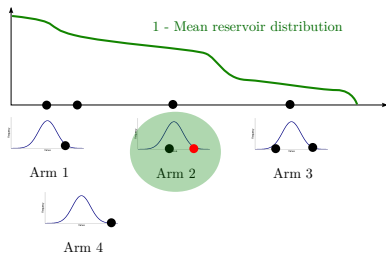
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 6$:



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

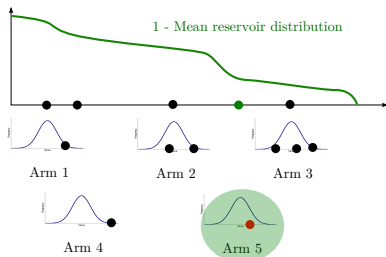
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 7$:



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

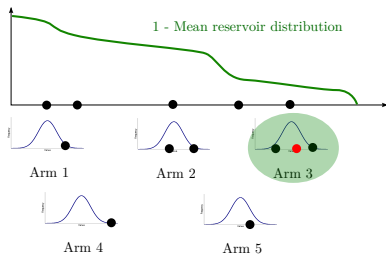
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 8$:



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

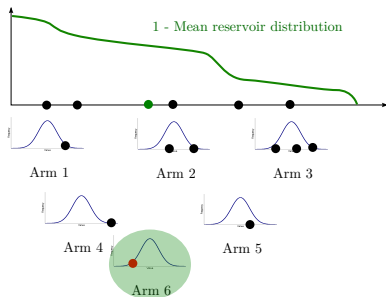
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t = 9$:



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

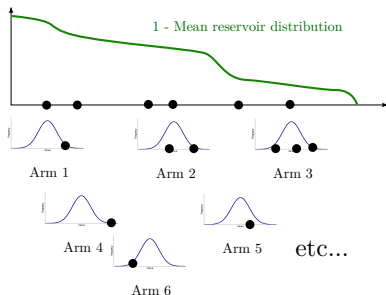
At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

At time $t... :$



No topology setting

- ▶ Arm reservoir distr. and an associated mean reservoir distr. F
- ▶ Limited sampling resources n , and $K_0 = 0$ observed arms

At time $t \leq n$ one can either

- ▶ set $K_t = K_{t-1} + 1$ and sample a new arm ν_{K_t} from the reservoir distr. with mean $\mu_{K_t} \sim F$, and set $I_t = K_t$,
- ▶ or choose an arm I_t among the K_{t-1} observed arms $\{\nu_k\}_{k \leq K_{t-1}}$,

and then collect $X_t \sim \nu_{k_t}$

Objective : Maximize $\sum_t X_t$.

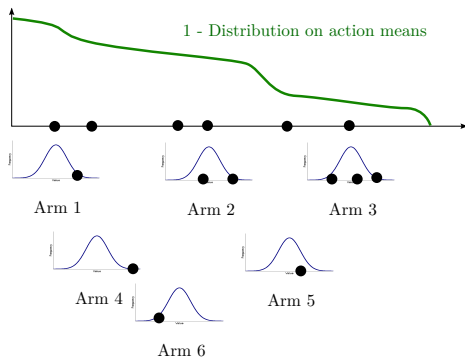
Double exploration and exploitation dilemma here :

Allocation both to (i) learn the characteristics of the arm reservoir distr. (*meta-exploration*) and (ii) learn the characteristics of the arms (*exploitation*) and (iii) to maximize the sum of rewards (*exploitation*).

Main questions

How many arms should be sampled from the arm reservoir distribution?
How aggressively should these arms be explored? What should be left for exploitation?

No topology : UCB-based (UCB-AIR) algorithm



Idea : Sub-sample the actions uniformly at random and adapt the number of actions to the proportion of sub-optimal actions.

No Topology : Regret analysis

Algorithm UCB-AIR : sub-sample $K_n \approx n^{\min(\beta/2, \beta/(\beta+1))}$ arms and sample the arm that maximize an UCB.

Theorem ((Wang, Audibert, Munos, 2008))

Assume that $\exists \beta > 0$ such that

$$\mathcal{P}(\mu(\text{new arm}) > \mu^* - \epsilon) \approx C\epsilon^\beta.$$

Then the expected regret of UCB-AIR is bounded as

$$\mathbb{E}R_n \leq C \max(\sqrt{n}, n^{\frac{\beta}{1+\beta}}).$$

Extensions : optimisation [C and Valko, 2015].

No topology and optimisation [C and Valko, 2015]

Problem: Return an arm \hat{k}_n such that $\mu_{\hat{k}_n}$ is as large as possible.

Algorithm SiRI : sub-sample $K_n \approx n^{\min(\beta, 2)/2}$ arms and sample the arm that maximize an UCB.

Theorem (C and Valko, 2015)

For SiRI we have up to $\log(n)$ factors

$$\mathbb{E}(\mu^* - \mu_{\hat{k}_n}) \leq \left(\max \left(n^{-1/2}, n^{-\frac{1}{\beta}} \right) \right).$$

Conclusion

Depending on the assumptions, many possible strategies.

Importance of :

- ▶ Minimal model assumptions
- ▶ Computational efficiency and simplicity
- ▶ Minimal calibration and versatility

Challenges :

- ▶ Good context integration
- ▶ Right assumptions
- ▶ Estimation of the regret of the strategies